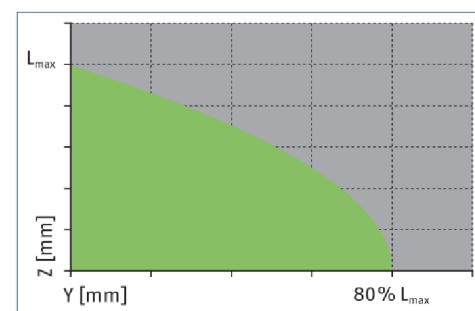
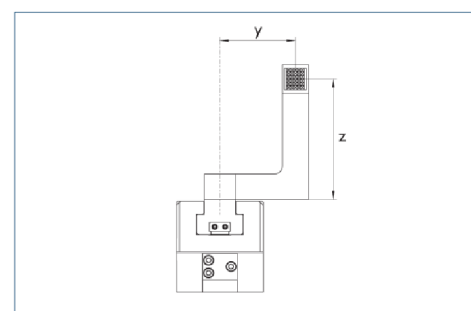
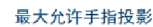
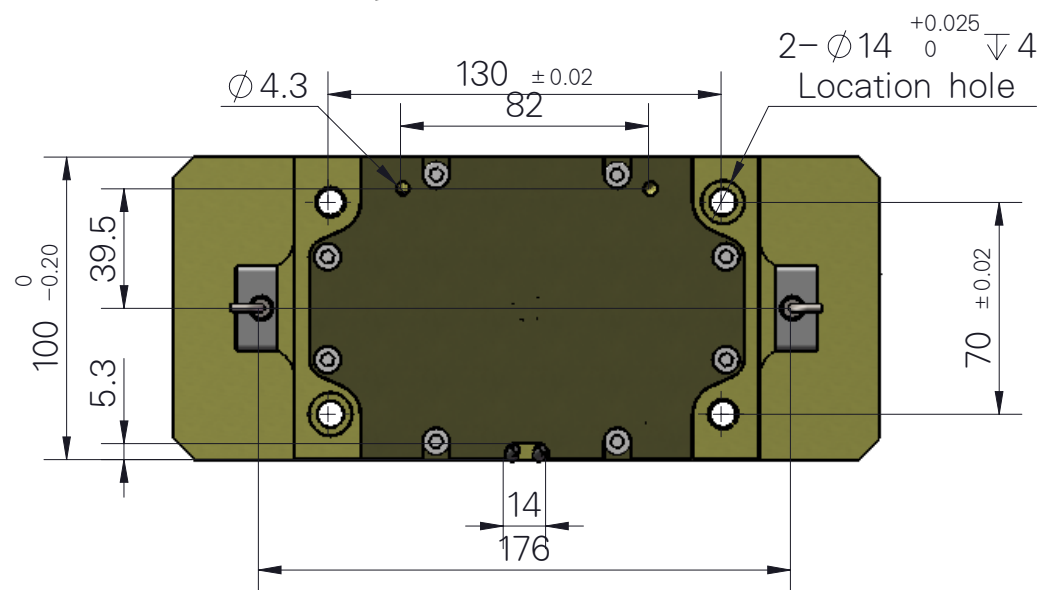
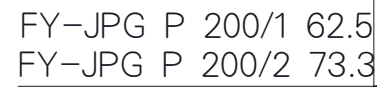




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Without further notice if specification and exterior have been changed because of improvement thanks for your understanding



允许的范围
 不允许的范围

L_{max} 等于最大允许手指长度。请参见技术参数表。

FY-JPG-P-200/1	76...126
FY-JPG-P-200/2	76...104

抓取力

— JGP-P 200 / 6 bar — JGP-P 200-AS / 6 bar
— JGP-P 200 / 4 bar — JGP-P 200-AS / 4 bar

F [N]

L [mm] 50 100 150 200 250 300

手指长度

Finger Length L [mm]	JGP-P 200 / 6 bar [N]	JGP-P 200-AS / 6 bar [N]	JGP-P 200 / 4 bar [N]	JGP-P 200-AS / 4 bar [N]
50	4000	5200	2700	3400
100	3700	5000	2500	3200
150	3400	4800	2300	3000
200	3200	4600	2100	2800
250	3000	4400	1900	2600
300	2800	4200	1700	2400

抓取力

Legend:

- JGP-P 200 / 6 bar
- JGP-P 200-IS / 6 bar
- JGP-P 200 / 4 bar
- JGP-P 200-IS / 4 bar

Y-axis: F [N] (0 to 6000)

X-axis: L [mm] (0 to 300)

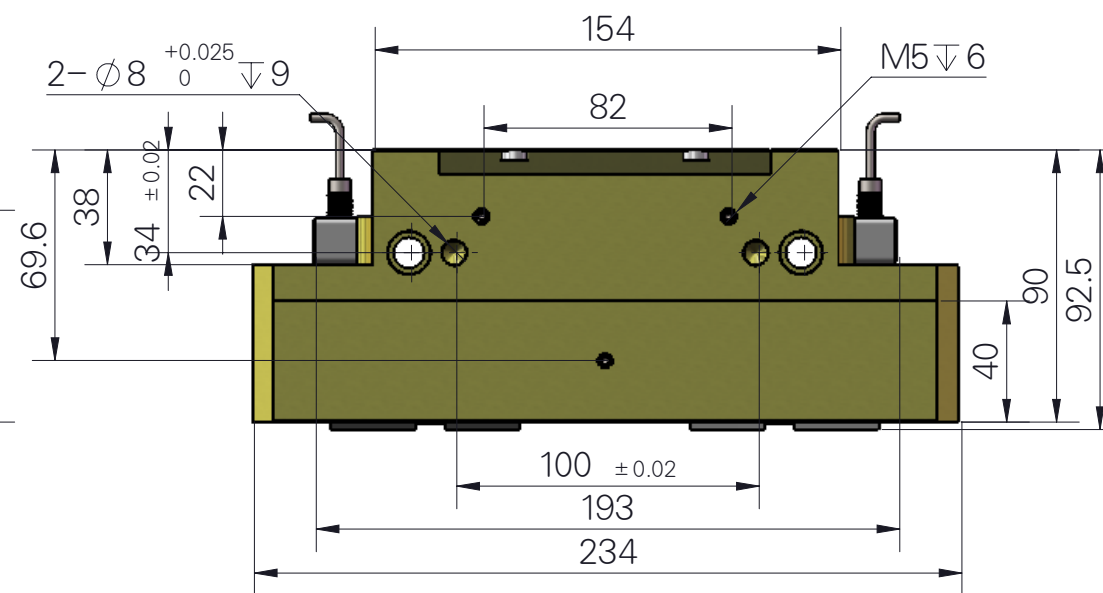
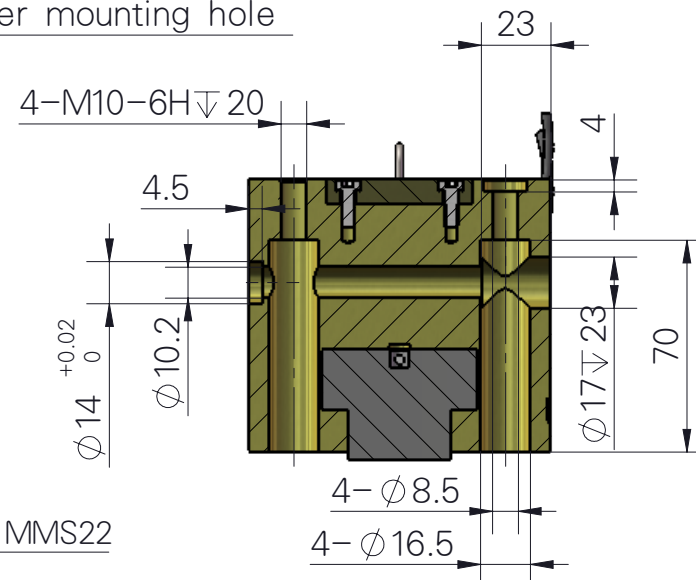
手指长度

A 3D perspective diagram of the 1000 Series Servo Motor. The motor is shown with its dimensions and load capacity. The coordinate system is defined by X, Y, and Z axes. The load capacity is indicated by colored squares and text:

- Mx** (Pink square): Mx 最大 194 Nm
- My** (Green square): My 最大 180 Nm
- Mz** (Grey square): Mz 最大 225 Nm
- Fz** (Dark Grey square): Fz 最大 10800 N

① 所示力矩和力为静态值, 适用于每个基爪, 且可能会同时出现。除抓取力自身产生的力矩外, 还可能产生负载。

推荐的工件重量 (Recommended workpiece weight) : 19kg



After 100 consecutive strokes to end positions

2. Because different objects have different friction coefficients, When clamping the workpiece for the first time, please try clamping in an open field. Ensure that the clamping is firm before the machine can work, otherwise it will There is a risk that falling workpieces may damage machines or personnel.